## Supplemental Material for "Online Linear Models for Edge Computing"

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This file contains proofs and figures that are described in Sections 4 and 5 but are not included there due to lack of space.

## Proof of Bounding Prediction of New Model

This is a proof of Lemma 1 from Section 4.2:

**Lemma 1.** Let  $\beta_1^*, \beta_2^*$  and r be as in Theorem 1, and let x be a sample. Then the upper and lower bounds on the prediction of  $\beta_2^*$  for x are:

$$L(x^{T}\beta_{2}^{*}) := \min_{\beta \in \Omega} x^{T}\beta = x^{T}\beta_{1}^{*} - x^{T}r - \|x\|\|r\|$$
(7a)

$$U(x^{T}\beta_{2}^{*}) := \max_{\beta \in \Omega} x^{T}\beta = x^{T}\beta_{1}^{*} - x^{T}r + ||x|| ||r||.$$
(7b)

*Proof.* Every vector  $\beta$  in the sphere  $\Omega$  could be represented as the sum of two vectors: the vector m, which is the center of the sphere, and vector u that starts from the center of the sphere and whose magnitude is bounded by the sphere radius vector ( $||u|| \leq ||r||$ ). Therefore, the dot product between  $\beta$  and a given x is

$$x^T \beta = x^T (m + u) = x^T m + x^T u = x^T m + ||x|| ||u|| \cos \left( \angle (x, u) \right).$$

The minimum of the dot product  $x^T\beta$ , with respect to u, is obtained when ||u|| = ||r|| and  $\cos(\angle(x, u)) = -1$ , i.e., u is a vector in the opposite direction of x and with the maximum magnitude under the constraint that u is on the sphere. In this case the lower bound is obtained,

$$L(x^T \beta_{new}^*) = x^T m - ||x|| ||r||.$$
(8)

Using similar arguments, the maximum of the dot product  $x^T\beta$  is obtained when ||u|| = ||r|| and  $\cos(\angle(x, u)) = 1$ . This time u is in the same direction as x. In this case the upper bound is obtained,

$$U(x^T \beta_{new}^*) = x^T m + ||x|| ||r||.$$
(9)

By substituting  $m = \beta_1^* - r$  (from definition of  $\Omega$  in Section 4.1) in the above expressions of the lower and upper bounds, we obtain (7).

Figure 4 shows these vectors in two dimensions, the sphere  $\Omega$ , and the vectors on its surface that yield the maximum and minimum dot product with x.

See Okumura et al. [21] for an alternative derivation of these bounds in a different form.



**Fig. 4.** Illustration of Lemma 1. Vector  $v_1$  is the vector in the circle that maximizes the projection on vector x, while  $v_2$  minimizes the projection on x. The projections of  $\beta_1^*$  and  $\beta_2^*$  on x are always between the projection of  $v_1$ , and  $v_2$ .

## Reanalysis of Okumura et al. [21] Bound to $\|\beta_1^* - \beta_2^*\|$

Okumura et al. suggest in their paper [21] an upper bound to the distance between models  $\|\beta_1^* - \beta_2^*\|$ . By reanalysis of their bound we show that the new bound we describe in Theorem 1 is tighter.

In [21, Section 2.2], a one-hot vector  $e_j$ ,  $j \in [d]$  where d is the dimension of x, is used to compute the upper and lower bounds of the  $j^{th}$  element of the new classifier  $-\beta_{2,j}^*$ . Then, by [21, Corollary 2]:

$$\|\beta_1^* - \beta_2^*\|_q \le \left(\sum_{j \in [d]} \max\{\beta_{1,j}^* - L(\beta_{2,j}^*), U(\beta_{2,j}^*) - \beta_{1,j}^*\}^q\right)^{\frac{1}{q}}$$
(10)

where  $\|\cdot\|_q$  is the  $L_q$  norm. The lower and upper bounds,  $L(\beta_{2,j}^*)$  and  $U(\beta_{2,j}^*)$ , are as in (7) for  $x = e_j$ . Assignment of  $x = e_j$  in (7) gives:

$$L(\beta_{2,j}^*) = \beta_{1,j}^* - r_j - ||r||$$
$$U(\beta_{2,j}^*) = \beta_{1,j}^* - r_j + ||r||.$$

Therefore:

$$\beta_{1,j}^* - L(\beta_{2,j}^*) = r_j + ||r||$$
$$U(\beta_{2,j}^*) - \beta_{1,j}^* = -r_j + ||r||$$

If  $r_j \ge 0$  then  $\beta_{1,j}^* - L(\beta_{2,j}^*) \ge ||r||$ , otherwise  $U(\beta_{2,j}^*) - \beta_{1,j}^* \ge ||r||$ . Therefore:

$$\max\{\beta_{1,j}^* - L(\beta_{2,j}^*), U(\beta_{2,j}^*) - \beta_{1,j}^*\} \ge \|r\|.$$
(11)

Using (11) with (10) gives:

$$\left(\sum_{j\in[d]}\max\{\beta_{1,j}^* - L(\beta_{2,j}^*), U(\beta_{2,j}^*) - \beta_{1,j}^*\}^q\right)^{\frac{1}{q}} \ge \left(\sum_{j\in[d]} \|r\|^q\right)^{\frac{1}{q}} = d^{\frac{1}{q}}\|r\|.$$

In general, for every  $d > 2^q$  the bound  $\|\beta_1^* - \beta_2^*\| \le 2\|r\|$  is tighter than (10). Specifically, for  $L_2$  norm, for any d > 4 the bound is tighter.

## **Evaluation Figures**



**Fig. 5.** Sine1+ dataset with 50 attributes and different scale ( $\sigma$ ) values. As with 2 attributes, the incremental based algorithms' performance is affected by  $\sigma$ .

Figure 5 shows that the effect of  $\sigma$  does not depend on the number of attributes. See Section 5.4 for description and analysis.